

A : Short Questions Section

(P01)

Q1.) SHO is any system whose eqn of motion (EOM) is $\ddot{x} + \omega_0^2 x = 0$ where $x(t)$ is the position of particle and $\omega_0 =$ angular frequency of oscillation

Q2.) Damped SHO is a system whose EOM is

$\ddot{x} + 2\gamma \dot{x} + \omega_0^2 x = 0$; where $x(t) =$ position of particle, 2γ measures "strength" of damping, and ω_0 is angular frequency the system would oscillate with in absence of damping.

(SHO + damping gives damped SHO.)

Q3.) In under-damped SHO,

• Amplitude decreases over time

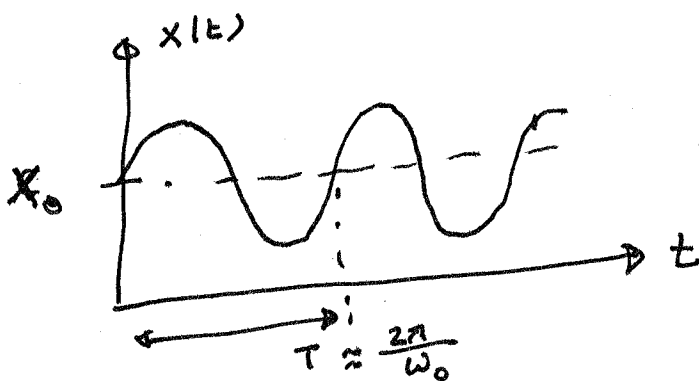
But • Angular frequency remains constant over time.

Q4.) SHO subjected to $F(t) = C \cos(\omega t) + C_0$

↗
external force

$\omega \gg \omega_0$

↖ Natural angular frequency.



↖ Fast $F(t)$ oscillation

Averages to a constant

⇒ Like a constant force acting on a particle

⇒ Doesn't affect frequency of oscillation

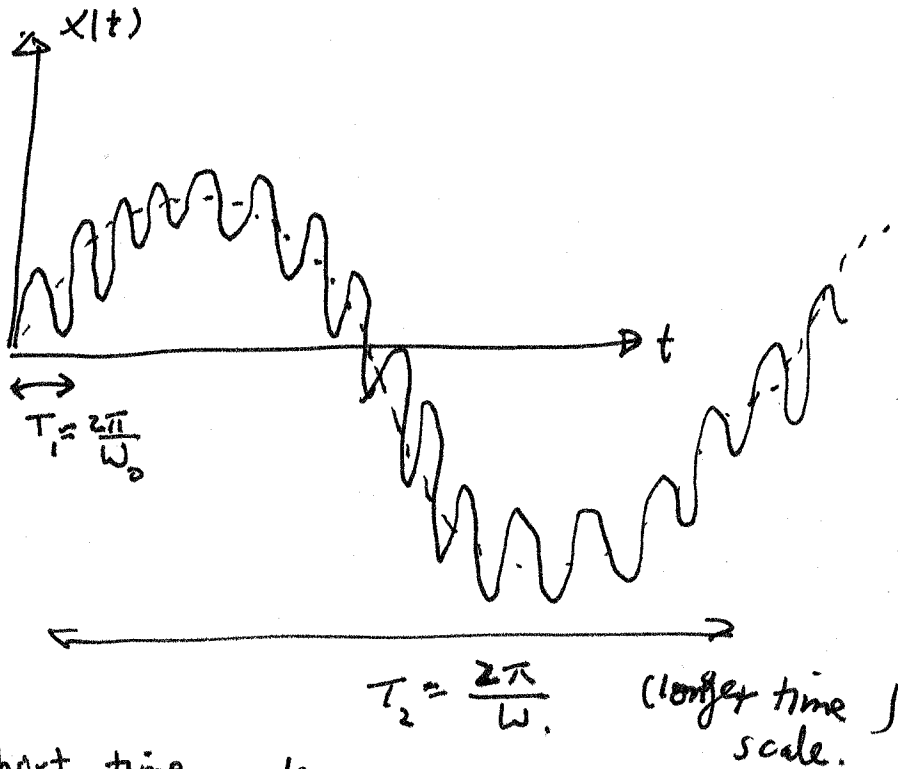
still ω_0

(Q5)

$$F(t) = (C_0 + C_1 \cos(\omega t))$$

$$\omega \ll \omega_0$$

Slowly varying sinusoidal force.



• On a short time scale,

looks like \sim constant force.

Only on a longer time scale, see the effect of

$F(t)$ oscillating with angular frequency ω .

System of

(Q6.)

N eqns of motion describe coupled oscillators of N particles.

- There are $2 \times N$ free parameters in the general sol'n.

Q7.)

(P93)

To find the normal modes:

Guess:
$$\begin{pmatrix} z_1(t) \\ z_2(t) \\ \vdots \\ z_N(t) \end{pmatrix} = \begin{pmatrix} A_1 \\ A_2 \\ \vdots \\ A_N \end{pmatrix} e^{i\omega t}$$

ω = Normal mode angular frequency.

↑
Column vector of N constants.

Then plugging this into the system of N EOMs, we can find ω .

• For N particles \Rightarrow N normal modes.

• General sol'n = $\sum_{n=1}^N (\text{Normal mode})_n$

↑
Linearity of this system of EOMs allow us to do this

Linearity means that if $y_1(t)$ and $y_2(t)$ are each individually solution to the ~~system~~ EOM, then so is $y_1(t) + y_2(t)$.

Q8.)

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To derive wave eqn from a coupled oscillator of N particles (e.g. slinky of N particles),

• Write down EOM for each particle. (from Newton's 2nd law)

• Then take the continuum limit to turn the EOMs to a single wave eqn.

- Continuum limit: $N \rightarrow \infty$. (Take N large) while keeping the total length L of the system fixed and finite.

$\Rightarrow a = \frac{L}{N} \Rightarrow a \rightarrow \text{infinitesimal} \Rightarrow a \equiv \delta x$
 \uparrow
 distance between 2 adjacent particles in equilibrium in the slinky.

Then the finite difference eqn of the form $\frac{y_j(t) - y_{j-1}(t)}{a}$
 becomes $\frac{\partial y(x_j, t)}{\partial x}$.

~~Sign~~ Also, we can then drop the subscript "j"

and write $x_j \rightarrow x$ because $x_{j+1} - x_j = a = \delta x$.
 discrete variable continuous variable

Q9.) $y(x, t) = A \exp(k(x - vt))$ is not sol'n for a string Pg 5

between 2 walls. because it doesn't satisfy the Boundary conditions

$$y(x=0, t) = 0$$

$$\text{and } y(x=L, t) = 0.$$

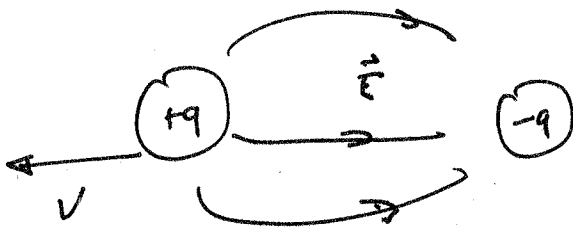
Q10) No, not a sol'n to wave eq'n. even w/o boundary conditions. because you cannot get $A e^{kx^2} e^{k(vt)^2}$ just by

using the substitution $z = x \pm vt$

i.e. Not of the form $y(x, t) = f(x \pm vt)$.

• It's not describing a periodic wave thro.

Q11)

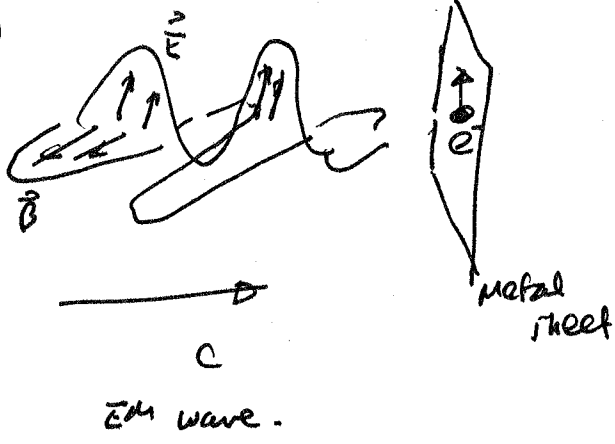


↑
move this charge. Then this charge must somehow "feel" displacement of "+q". ↑ Takes finite time to travel (Not instantaneously)

from +q to -q charge.

⇒ EM wave generated.

Q12.)



P96

\vec{E} & \vec{B} components of EM wave

does work on free electron in the metal.

⇒ Energy is transferred to e^- .

⇒ Wave dies away.

Q13)

V_{max} occurs at $x=0$. (spring ~~unextended~~ in equilibrium)
 configuration when $x=0$.
 \parallel
 2 m/s .

$$E_{tot} = KE_{max} = \frac{mV_{max}^2}{2} = \frac{(1 \text{ kg})(2 \text{ m/s})^2}{2} = \boxed{2 \text{ J}}$$

$$\frac{KA^2}{2} \Rightarrow 4 \text{ J} = KA^2$$

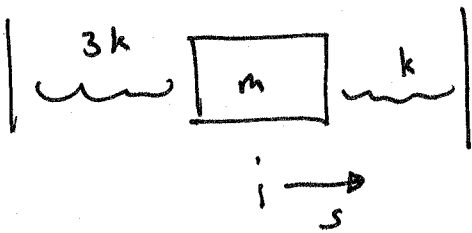
$$\Rightarrow K = \frac{4}{1} \text{ N/m} \Rightarrow \boxed{K = 4 \text{ N/m}}$$

II. Problems

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P1

(a) Ignore gravity since $s(t) \equiv$ displacement from equilibrium
(i.e. $s=0$ equilibrium).



$$m\ddot{s} = -ks - 3ks$$
$$\Rightarrow \ddot{s} + \left(\frac{4k}{m}\right)s = 0$$

$$\Rightarrow \ddot{s} + \omega_0^2 s = 0$$

$$\omega_0 = \sqrt{\frac{4k}{m}}$$

↑
Natural angular frequency

(b) General soln : $s(t) = S_0 \cos(\omega_0 t - \phi)$

2 free parameters : $S_0 \equiv$ Amplitude

$\phi \equiv$ phase shift.

(c) $E_{\text{tot}} = \frac{m\dot{s}^2}{2} + \frac{\cancel{3k} + \cancel{3k}}{2} k_{\text{eff}} s^2$

$$= \frac{m\dot{s}^2}{2} + 2ks^2$$

$$k_{\text{eff}} = 4k$$

can also get from

$$PE_{\text{tot}} = \frac{ks^2}{2} + \frac{3ks^2}{2} = 2ks^2$$

(Cd) Conservation of energy $\Rightarrow \frac{dE_{\text{tot}}}{dt} = 0$.

$$\Rightarrow 0 = \frac{d}{dt} \left(\frac{m\dot{s}^2}{2} + 2ks^2 \right)$$

$$= \frac{m}{2} 2\dot{s}\ddot{s} + 4ks\dot{s}$$

$$= \dot{s} [m\ddot{s} + 4ks] \quad \text{But } \dot{s}(t) \neq 0 \text{ for some } t.$$

$$\Rightarrow 0 = m\ddot{s} + 4ks$$

$$\Rightarrow 0 = \ddot{s} + \left(\frac{4k}{m} \right) s$$

$$\Rightarrow 0 = \ddot{s} + \omega_0^2 s$$

(ce) $F = -b\dot{s}$
damp

EOM: Newton's 2nd law:

$$m\ddot{s} = F_{\text{spring}} + F_{\text{damping}}$$

$$= -ks - 3ks - b\dot{s}$$

$$\Rightarrow \ddot{s} + \underbrace{\left(\frac{b}{m} \right)}_{2\gamma} \dot{s} + \left(\frac{4k}{m} \right) s = 0$$

$$\Rightarrow \ddot{s} + (2\gamma)\dot{s} + \omega_0^2 s = 0$$

$$\gamma = \frac{b}{2m}$$

(f)

① verman of EOM :

$$\underset{\text{IR}}{S} \rightarrow \underset{\mathbb{R}}{\tilde{S}}$$

$$\ddot{\tilde{S}} + 2\gamma\dot{\tilde{S}} + \omega_0^2\tilde{S} = 0$$

Given : $\tilde{S}(t) = Ae^{i\omega t}$

plug in $\Rightarrow -\omega^2 + 2i\gamma\omega + \omega_0^2 = 0$

$$\Rightarrow \omega_{\pm} = \frac{-2i\gamma \pm \sqrt{-4\gamma^2 + 4\omega_0^2}}{-2}$$

$$\Rightarrow \boxed{\omega_{\pm} = i\gamma \pm \underbrace{\sqrt{\omega_0^2 - \gamma^2}}_{\tilde{\omega}}}$$

So:

$$\tilde{S}(t) = A e^{-\gamma t} e^{i\tilde{\omega}t} + B e^{-\gamma t} e^{-i\tilde{\omega}t}$$

$$= \boxed{e^{-\gamma t} [A e^{i\tilde{\omega}t} + B e^{-i\tilde{\omega}t}]}$$

* Block comes to rest fastest w/o oscillating when critically damped.

This occurs when $\tilde{\omega} = 0 \Rightarrow \boxed{\omega_0 = \gamma}$

(g)

When underdamped, $\tilde{\omega}$ is real so extracting the real solution

we get:

$$Ae^{i\tilde{\omega}t} + Be^{-i\tilde{\omega}t}$$

 \rightarrow

$$C \cos(\tilde{\omega}t - \phi)$$

↑ Amplitude

$$\Rightarrow \boxed{S(t) = C e^{-\gamma t} \cos(\tilde{\omega}t - \phi)}$$

$$\Rightarrow \text{Amplitude}(t) = C e^{-\gamma t}$$

\Rightarrow Maximum heat energy that can be delivered at $t = \frac{2}{\gamma}$ is:

$$\Delta E = \frac{1}{2} k_{\text{eff}} (\text{Amplitude})^2 (t = \frac{2}{\gamma}) - E(t=0) \quad k_{\text{eff}} = 4k$$

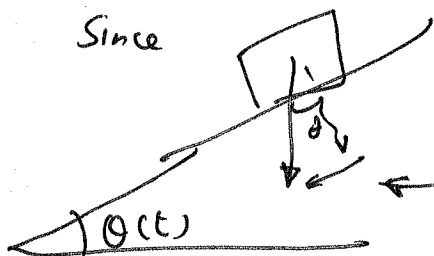
$$= \frac{4k}{2} [C^2 e^{-2\gamma t}] - \frac{4k}{2} C^2$$

$$= 2kC^2 [e^{-2\gamma(\frac{2}{\gamma})} - 1] = 2kC^2 [e^{-4} - 1] < 0,$$

maximal
 \therefore Heat delivered is $\boxed{2kC^2 [1 - e^{-4}]}$

$\boxed{\text{Ch}}$ This becomes a forced simple harmonic oscillator.

Since



\leftarrow this force is $mg \sin \theta$

$$\approx mg \sin(\theta_0 \cos(\omega t))$$

$$F(t) \approx (mg \theta_0) \cos(\omega t) \quad \text{since } |\theta_0| \ll 1.$$

If $\frac{2\pi}{\omega} = 2 \text{ yrs}$ and $\frac{2\pi}{\omega_0} = 1 \text{ sec}$

$\Rightarrow \underline{\omega \ll \omega_0} \Rightarrow$ On a short time scale, looks like a constant force. but on a longer time scale, can see the effect of θ oscillating w/ ω .

$$\Rightarrow \boxed{T_{\text{block}} \approx \frac{2\pi}{\omega_0} = 1 \text{ sec.}}$$

P2.

(a) Consider $g(z)$ to be any one-variable (z) function.

Then let $z = x \pm vt$.

Check if $g(x \pm vt)$ satisfies wave eqn.

Check: LHS: $\frac{\partial^2 g(x \pm vt)}{\partial t^2} = \frac{\partial}{\partial t} \left[\frac{dg}{dz} \cdot \frac{\partial z}{\partial t} \right]$ " $g'(z)$ "

$$= (\pm v) \frac{\partial}{\partial t} [g'(z)]$$

$$= (\pm v) \left[g''(z) \frac{\partial z}{\partial t} \right]$$

" $g''(z)$ " " $\frac{\partial z}{\partial t}$ "
" $(\pm v)$ "

$$= v^2 g''(z).$$

RHS: $v^2 \frac{\partial^2 g(x \pm vt)}{\partial x^2}$

$$= v^2 \frac{\partial}{\partial x} \left[\frac{dg}{dz} \cdot \frac{\partial z}{\partial x} \right] = v^2 \frac{\partial}{\partial x} g'(z)$$

$$= v^2 g''(z)$$

\Rightarrow LHS = RHS

$\therefore g(x+vt)$ & $g(x-vt)$ solutions to wave eqn.

$$\Rightarrow \boxed{f(x,t) = g(x-vt) + g(x+vt)} \text{ sol'n to wave eqn.}$$

(b)

$$\tilde{f}(x,t) = \tilde{A} e^{i(kx - \omega t)}$$

Pg 12

where

$$\omega = \frac{kV}{2}$$

↳ corresponding wave eqn:

$$\frac{\partial^2 \tilde{f}}{\partial t^2} = \left(\frac{V}{2}\right)^2 \frac{\partial^2 \tilde{f}}{\partial x^2}$$

(c)

Incident: $y_i(x,t) = A_i e^{i(k_1 x - \omega t)}$

Reflected: $y_r(x,t) = A_r e^{i(k_1 x - \omega t)}$

Transmitted: $y_t(x,t) = A_t e^{i(k_2 x - \omega t)}$

$$k_1 = \frac{2\pi}{\lambda_A}$$

$$k_2 = \frac{2\pi}{\lambda_B}$$

$\lambda_A \equiv$ wavelength in string A

$\lambda_B \equiv$ wavelength in string B.

(d)

Resultant wave in A: $y_1(x,t) = y_i + y_r$
 $= [A_i e^{ik_1 x} + A_r e^{-ik_1 x}] e^{-i\omega t}$

Resultant wave in B: $y_2(x,t) = y_t(x,t)$
 $= A_t e^{i(k_2 x - \omega t)}$

(C) 2 Boundary conditions (BCs)

BC1: 2 strings are joined at $x=0$

$$\Rightarrow y_1(0, t) = y_2(0, t)$$

$$\Rightarrow \boxed{A_i + A_r = A_t}$$

BC2: No kinks (smooth joint) at the joint:

$$\frac{\partial y_1}{\partial x} \Big|_{x=0} = \frac{\partial y_2}{\partial x} \Big|_{x=0}$$

$$\Rightarrow \boxed{k_1(A_i - A_r) = k_2 A_t}$$

(F) If density of B \gg density of A;

then transmitted wave disappears. $\Rightarrow A_t \rightarrow 0$.

Then BC1 gives $A_i + A_r \approx 0 \Rightarrow \boxed{A_i = -A_r}$

P3

Ca

2 Guesses

(1) $y_1(x,t) = A \cos(kx) e^{-i\omega t}$

(2) $y_2(x,t) = B \sin(kx) e^{-i\omega t}$

2 BCs: $y(0,t) = 0$; $y(L,t) = 0$.

For Guess (1): $y_1(0,t) = 0 \Rightarrow A = 0 \Rightarrow y_1(x,t) = 0$

For guess (2): $y_2(0,t) = 0$ ✓ automatically satisfied since $\sin(0) = 0$.

and, $y_2(x=L,t) = 0 = B \sin(kL) e^{-i\omega t}$

$\Rightarrow kL = n\pi \quad n = 1, 2, 3, \dots$

$\Rightarrow \boxed{k_n = \frac{n\pi}{L}}$

$\Rightarrow \boxed{\omega_n = k_n v} = \frac{n\pi v}{L}$

$\therefore y_n(x,t) = y_{1,n}(x,t) + y_{2,n}(x,t) = B_n \sin(k_n x) e^{-i\omega_n t}$ is sol'n.

To extract real ~~part of answer~~ solution

Using procedure discussed in class, expand $e^{-i\omega t}$

$\Rightarrow \boxed{y_n(x,t) = \left\{ A_n \cos\left(\frac{n\pi vt}{L}\right) + B_n \sin\left(\frac{n\pi vt}{L}\right) \right\} \sin\left(\frac{n\pi x}{L}\right)}$

indeed.

(b)

$$y(x,t) = \sum_{n=1}^{\infty} y_n(x,t)$$

(P915)

↑ general solution.

(c)

Can just "read off" the coefficients from $g(x)$ & $h(x)$.

$$\text{so: } g(x) = y(x=0,t) = \sum_{n=1}^{\infty} y_n(0,t) = \sum_{n=1}^{\infty} A_n \sin\left(\frac{n\pi x}{L}\right)$$

$$\parallel$$

$$\frac{L}{4} \sin\left(\frac{4\pi x}{L}\right) - \frac{L}{3} \sin\left(\frac{18\pi x}{L}\right) \quad \swarrow \text{match.}$$

$$\Rightarrow \boxed{A_4 = \frac{L}{4}, \quad A_{18} = -\frac{L}{3}, \quad A_m = 0 \text{ for } m \neq 4, 18}$$

$$h(x) = \left. \frac{\partial y}{\partial t} \right|_{t=0} = \sum_{n=1}^{\infty} \left. \frac{\partial y_n}{\partial t} \right|_{t=0}$$

$$\parallel = \sum_{n=1}^{\infty} \underbrace{(\omega_n B_n)}_{C_n} \sin\left(\frac{n\pi x}{L}\right)$$

$$\frac{V_0}{5} \sin\left(\frac{16\pi x}{L}\right) + \frac{V_0}{2} \sin\left(\frac{2\pi x}{L}\right)$$

$$\Rightarrow C_{16} = \frac{V_0}{5} \Rightarrow B_{16} = \frac{C_{16}}{\omega_{16}} = \frac{V_0}{5} \frac{L}{16\pi V}$$

$$= \boxed{\frac{V_0 L}{80\pi V}}$$

$$\Rightarrow C_2 = \frac{V_0}{2} \Rightarrow B_2 = \frac{C_2}{\omega_2} = \frac{V_0}{2} \frac{L}{2\pi V} = \boxed{\frac{V_0 L}{4\pi V}}$$

$$B_2 = \frac{V_0 L}{4\pi v} \quad , \quad B_{16} = \frac{V_0 L}{80\pi v} \quad , \quad B_m = 0 \text{ for } m \neq 2, 16.$$

~~$y(x,t) = A_4 \cos(\omega_4 t)$~~

For $t > 0$:

$$y(x,t) = \sum_{n=1}^{\infty} \left[A_n \cos\left(\frac{n\pi v t}{L}\right) + B_n \sin\left(\frac{n\pi v t}{L}\right) \right] \sin\left(\frac{n\pi x}{L}\right)$$

with the A_n & B_n determined above.

(d) $g(x) = \frac{L}{4} \sin\left(\frac{8\pi x}{2L}\right) - \frac{L}{3} \sin\left(\frac{18\pi x}{L}\right)$

$$= \frac{L}{4} \sin\left(\frac{8\pi x}{2(L/2) \cdot 2}\right) - \frac{L}{3} \sin\left(\frac{18\pi x}{2(L/2)}\right)$$

$$= \frac{L}{4} \sin\left(\frac{2\pi x}{(L/2)}\right) - \frac{L}{3} \sin\left(\frac{9\pi x}{(L/2)}\right)$$

$\Rightarrow A_2 = L/4 \quad A_9 = -L/3 \quad A_m = 0 \text{ for } m \neq 2, 9$

$$h(x) = \frac{V_0}{5} \sin\left(\frac{8\pi x}{L/2}\right) + \frac{V_0}{L} \sin\left(\frac{\pi x}{(L/2)}\right)$$

$\Rightarrow B_8 = \frac{V_0}{5\omega_8} \quad B_1 = \frac{V_0}{2\omega_1} \quad B_m = 0 \text{ for } m \neq 1, 8.$